## **Secondary Side** Synchronous Flyback Controller

The NCP4302 is a full featured controller and driver that provide all the control and protection functions necessary for implementing a synchronous rectifier operation in a flyback converter. With the use of the NCP4302, the space conscious flyback applications such as Adaptors, chargers, set top boxes can achieve significant efficiency improvements at minimal extra cost. In addition to the synchronous rectifier control, the IC incorporates an accurate TL431 type shunt regulator, current monitoring circuit and optocoupler driver to provide a single IC secondary solution. The NCP4302 works with any type of flyback topology (continuous mode, Quasi-resonant mode or discontinuous mode) – providing a high level of versatility.

#### Features

- Self-contained Control of Synchronous Rectifier in CCM, DCM, and **QR** Flyback Applications
- Interface to External Signal for CCM Mode
- True Secondary Zero Current Detection
- High Gate Drive Currents (2.5 A Source/Sink)
- High Voltage Operation
- Current Sense Flexibility (MOSFET R<sub>DS(on)</sub> OR CS Resistor)
- Accurate Low Voltage Reference - NCP4302A 2.55 V, 1%
  - NCP4302B 1.275 V, 1%
- Programmable Independent Secondary Side ton and toff Delays
- Maximum Frequency of Operation up to 250 kHz
- These are Pb-Free Devices

#### **Typical Applications**

- Notebook Adapters
- LCD TV Adapters
- Consumer Appliances such as DVD, VCR
- Power Over Ethernet Applications (IP phones, Wireless Access Points)
- Battery Chargers



## **ON Semiconductor®**





= Wafer Lot

L

Y

W

- = Year = Work Week
- = Pb-Free Package





#### **ORDERING INFORMATION**

| Device       | Package           | Shipping $^{\dagger}$ |
|--------------|-------------------|-----------------------|
| NCP4302ADR2G | SO-8<br>(Pb-Free) | 2500/Tape & Reel      |
| NCP4302BDR2G | SO-8<br>(Pb-Free) | 2500/Tape & Reel      |

+For information on tape and reel specifications, including part orientation and tape sizes, please refer to our Tape and Reel Packaging Specifications Brochure, BRD8011/D.

#### **PIN DESCRIPTION**

| Pin<br>Number Symbol |                    | Description   |  |  |  |
|----------------------|--------------------|---|--|--|--|
| 1                    | SYNC/CS            | Connected to the flyback winding. The current on this pin is sensed and used to turn on the Synchronous Rectification MOSFET (SRFET). This pin is also used to sense the zero crossing of the MOSFET current either using the $R_{DS(on)}$ of the SRFET or using an external current sense resistor connected between drain of the SRFET and the flyback winding. |  |  |  |
| 2                    | TRIG               | Input pin for direct turn-off of the MOSFET. Typically connected to a signal from primary controller (for CCM mode) or a signal derived from the transformer (for QR mode). Has very short propagation delay to output (<50 ns).  |  |  |  |
| 3                    | CATH               | Feedback compensation pin for the TL431 shunt regulator. Has the capability to sinking 10 ma of opto current.   |  |  |  |
| 4                    | V <sub>REF</sub>   | Output voltage feedback through resistive divider connected to this pin. Regulated at 1.28 V (option B) or 2.55 V (option A).   |  |  |  |
| 5                    | D <sub>LYADJ</sub> | A resistive divider between the power supply output and ground with the center point tied to the $D_{LYADJ}$ input pin allows for independent adjustment of the minimum $t_{on}$ and $t_{off}$ delay time. The maximum external capacitance from this pin to ground is 25 pF.   |  |  |  |
| 6                    | GND                | Return pin for the controller – connected to the output return.   |  |  |  |
| 7                    | DRV                | Drive output for external MOSFET – 2.5 A peak drive capability, internally clamped to 13.5 V (Maxim-<br>um)   |  |  |  |
| 8                    | V <sub>CC</sub>    | Bias voltage for the controller. Maximum voltage is 28 V.   |  |  |  |

#### **MAXIMUM RATINGS**

| Rating                                 | Symbol   | Value             | Unit    |
|--|--|-------------------|---------|
| Power Supply Input<br>Current          | V <sub>CC</sub><br>I <sub>CC</sub>             | -0.3 to 28<br>100 | V<br>mA |
| Drive Voltage<br>Current               | V <sub>DRV</sub>                               | -0.3 to 18<br>100 | V<br>mA |
| Drive Current<br>Source<br>Sink        | I <sub>DRV</sub>                               | 2.5<br>-2.5       | Apk     |
| Analog and Logic Inputs                | TRIG, V <sub>REF</sub> ,<br>D <sub>LYADJ</sub> | -0.3 to 10<br>100 | V<br>mA |
| Maximum Voltage<br>Current             | SYNC/CS  | - 10 to 95<br>100 | V<br>mA |
| Operating Junction Temperature Range   | TJ   | -40 to 125        | °C      |
| Maximum Junction Temperature           | T <sub>Jmax</sub>                              | 150               | °C      |
| Storage Temperature Range              | T <sub>Smax</sub>                              | -65 to 150        | °C      |
| Lead Temperature (Soldering, 10 s)     | T <sub>Lmax</sub>                              | 300               | °C      |
| Reference input Current, continuous    | IREF   | -0.05 to 10       | mA      |
| Total Power Dissipation                | PD   | 225               | mW      |
| Thermal Resistance Junction-to-Ambient | $\theta_{JA}$                                  | 178               | °C/W    |

Stresses exceeding Maximum Ratings may damage the device. Maximum Ratings are stress ratings only. Functional operation above the Recommended Operating Conditions is not implied. Extended exposure to stresses above the Recommended Operating Conditions may affect device reliability.

This device series contains ESD protection and exceeds the following tests: Pin 1–8: Human Body Model 2000 V per Mil–Std–883, Method 3015. Machine Model Method 200 V

2. This device contains Latch-up protection and exceeds  $\pm 100$  ma per JEDEC Standard JESD78

#### **ELECTRICAL CHARACTERISTICS**

 $(V_{CC} = 19 \text{ V}, \text{ Sync frequency} = 100 \text{ kHz}, V_{REF} = V_{KA} (I_{KA} = 1 \text{ mA}), R_S = 75 \text{ ohms}, V_{TRIG} = GND, C_{DRV} = 1 \text{ nF}, R_{DLYADJ} = 30.1 \text{ k}, V_{DLYADJ} = 2.0 \text{ V}, \text{ for typical values } T_J = 25^{\circ}\text{C}, \text{ for min/max values } T_J = -40^{\circ}\text{C} \text{ to } +125^{\circ}\text{C}, \text{ Max } T_J = 150^{\circ}\text{C}, \text{ unless otherwise noted})$ 

| Rating  | Test Conditions  | Symbol                   | Min | Тур  | Max  | Unit |
|---|--|--------------------------|-----|------|------|------|
| V <sub>CC</sub>   |  |                          |     |      |      |      |
| Start-up Threshold  | V <sub>CC</sub> ↑, SYNC/CS = 0 to -0.5 V<br>100 kHz, 5 μs pulse, Trig = 0 V  | V <sub>CC(on)</sub>      | 9.6 | 10.4 | 11.2 | V    |
| Stop Threshold  | $V_{CC}$ ↓, SYNC/CS = 0 to -0.5 V<br>100 kHz, 5 µs pulse, Trig = 0 V   | V <sub>CC(off)</sub>     | 8.5 | 9.2  | -    | V    |
| V <sub>CC</sub> shutdown Hysteresis                             | V <sub>CC(on)</sub> - V <sub>CC(off)</sub>   | V <sub>CC(HYS)</sub>     | 0.9 | 1.2  | 1.4  | V    |
| Supply current after turn-on                                    | no–load on DRV pin, SYNC/CS = 0 to –0.5 V 100 kHz, 5 $\mu s$ pulse, Trig = 0 V   | I <sub>CC1</sub>         | -   | 2.7  | 5.6  | mA   |
| Supply current after turn-on                                    | SYNC/CS = 0 to -0.5 V 100 kHz, 5 $\mu s$ pulse, Trig = 0 V   | I <sub>CC2</sub>         | -   | 3.6  | 7.5  | mA   |
| DRIVE OUTPUT  |  |                          |     |      |      |      |
| Output voltage rise-time  | 10–90% of the output signal SYNC/ CS = 0 to –0.5 V 100 kHz, 5 $\mu s$ pulse, Trig = 0 V  | t <sub>r</sub>           | -   | -    | 40   | ns   |
| Output voltage fall-time  | 10–90% of the output signal SYNC/ CS = 0 to –0.5 V, 100 kHz, 5 $\mu s$ pulse, Trig = 0 V   | t <sub>f</sub>           | -   | -    | 40   | ns   |
| Output source current (Note 3)                                  |  | I <sub>DRV(source)</sub> | I   | 2.5  | -    | Apk  |
| Driver high level output voltage                                | $I_{SOURCE}$ = 200 mA, SYNC/CS = 0 to –0.5 V 100 kHz, 5 $\mu s$ pulse, Trig = 0 V, $V_{CC}$ = 12 V   | V <sub>DRV(H)</sub>      | 6.5 | 9.5  | -    | V    |
| Output sink current (Note 3)                                    |  | I <sub>DRV(sink)</sub>   | -   | 2.5  | -    | Apk  |
| Driver Output low level output voltage                          | $I_{SINK}$ = 200 mA, SYNC/CS = 0 to<br>-0.5 V 100 kHz, 5 $\mu s$ pulse, Trig = 0 V,<br>$V_{CC}$ = 12 V   | V <sub>DRV(L)</sub>      | -   | 160  | 500  | mV   |
| Drive voltage internal clamp                                    | V <sub>CC</sub> = 28 V, SYNC/CS = 0 to -0.5 V<br>100 kHz, 5 μs pulse, Trig = 0 V,<br>DRVpin = 10 kΩ  | V <sub>DRV(CLMP)</sub>   | -   | -    | 17   | V    |
| Minimum drive output voltage                                    | $\label{eq:VCC} \begin{array}{l} V_{CC} = V_{CC(off)} + 200 \text{ mV, DRV pin} = \\ 10 \ k\Omega + 1 \ nF, \ SYNC/CS = 0 \ to \ -0.5 \ V \\ 100 \ kHz, \ 5 \ \mu s \ pulse, \ Trig = 0 \ V \end{array}$ | V <sub>DRV</sub> (MIN)   | 5.5 | 6.5  | -    | V    |
| SYNC/CS   | •  | •                        |     |      |      |      |
| The total propagation delay from SYNC/CS to the DRV output      | SYNC/CS = +0.5 V to -0.5 V 100 kHz,<br>5 $\mu$ s pulse, (Trig = 0 V)(Refer to the<br>Drive Output specifications for Tr 50%<br>of the output signal  | t <sub>p1</sub>          | -   | 70   | 135  | ns   |
| Zero Current Detection  | V <sub>SYNC/CS</sub> < -30 mV  | ls(zcd)                  | 50  | 230  | 450  | μΑ   |
| Current Sense Pin Offset Voltage at Zero Current Level (Note 3) |  | VS(ZCD)                  | -30 | -    | -    | mV   |
| SYNC/CS Leakage current   | V <sub>SYNC/CS</sub> = 95 V  | SCS <sub>Leakage</sub>   | -   | -    | 10   | μΑ   |
| TRIGGER SECTION   | 1  | 1                        |     | Ι    | 1    |      |
| Minimum Trigger pulse duration                                  | SYNC/CS = 0 to -0.5 V 100 kHz, 5 $\mu$ s pulse, Trig $\uparrow$  | trig-pw                  | 75  | -    | -    | ns   |

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#### **ELECTRICAL CHARACTERISTICS**

 $(V_{CC} = 19 \text{ V}, \text{ Sync frequency} = 100 \text{ kHz}, V_{REF} = V_{KA} (I_{KA} = 1 \text{ mA}), R_S = 75 \text{ ohms}, V_{TRIG} = GND, C_{DRV} = 1 \text{ nF}, R_{DLYADJ} = 30.1 \text{ k}, V_{DLYADJ} = 2.0 \text{ V}, \text{ for typical values } T_J = 25^{\circ}\text{C}, \text{ for min/max values } T_J = -40^{\circ}\text{C} \text{ to } +125^{\circ}\text{C}, \text{ Max } T_J = 150^{\circ}\text{C}, \text{ unless otherwise noted})$ 

| Rating   | Test Conditions   | Symbol                  | Min            | Тур        | Max            | Unit |
|--|---|-------------------------|----------------|------------|----------------|------|
| TRIGGER SECTION  |   |                         | -              |            | <u>-</u>       |      |
| Trigger Pulse Voltage for Gate turn-off  | SYNC/CS = 0 to -0.5 V 100 kHz, 5 $\mu$ s pulse, Trig $\uparrow$   | Vtrig                   | 2.0            | -          | 4.0            | V    |
| Propagation delay from TRIG to DRV turn-off  | C <sub>DRV</sub> = no-load, SYNC/CS= -0.5 V<br>100 kHz, 5 μs pulse, Trig = 0-5 V ↑  | t <sub>p2</sub>         | -              | 25         | 85             | ns   |
| TL431 CHARACTERISTICS  |   | •                       |                | •          |                |      |
| Reference input voltage  | I <sub>KA</sub> = 5 mA, V <sub>KA</sub> = V <sub>REF</sub><br>NCP4302A  | V <sub>REF</sub>        |                |            |                | V    |
|  | $T_J = +25^{\circ}C$<br>$T_J = -40^{\circ}C$ to +125°C  |                         | 2.525<br>2.499 | 2.55<br>-  | 2.575<br>2.60  |      |
| Reference input voltage  | $(I_{K} = 5 \text{ mA}, V_{KA} = V_{REF})$<br>NCP4302B<br>$T_{J} = +25^{\circ}C$<br>$T_{J} = -40^{\circ}C \text{ to } +125^{\circ}C$  | V <sub>REF</sub>        | 1.262<br>1.249 | 1.275<br>- | 1.288<br>1.301 | V    |
| Reference Input Current  | I <sub>KA</sub> = 10 mA   | I <sub>Ref</sub>        | -              | 0.0018     | 4.0            | μA   |
| Minimum CATH current for<br>regulation   | I <sub>SOURCE</sub> <sup>↑</sup> 0 to 1 mA  | I <sub>KA</sub>         | -              | 0.5        | 1.0            | mA   |
| Reference voltage line regulation  | $\Delta V_{KA} = V_{CCon} - 16 \text{ V},  I_{KA} = 1 \text{ mA}$ $= \frac{\Delta V_{REF}}{\Delta V_{KA}}$  | V <sub>KA</sub>         | -              | 2.0        | 5.0            | mV/V |
| Off-State CATH Current   | $V_{KA}$ = 18 V, $V_{REF}$ = 0 V (test circuit 2, $V_{REF}$ pin grounded)   | I <sub>Off</sub>        | -              | 11         | 20             | μΑ   |
| Dynamic impedance  | $V_{KA} = V_{REF}$ , $\Delta I_{KA} = 1$ mA to 10 mA  | Z <sub>KA</sub>         | -              | 0.62       | 1.5            | Ω    |
| The maximum sink current capability  | (I <sub>SOURCE</sub> ↑ 0 to 10 mA)  | Isinkmax                | 10             | -          | -              | mA   |
| ADJUSTABLE TIME DELAY  |   |                         |                |            |                |      |
| The t <sub>on</sub> time delay   | $\begin{array}{l} SYNC/CS = 0 \mbox{ to } -0.5 \mbox{ V } 100 \mbox{ kHz}, 5  \mu s \\ \mbox{ pulse, Trig = 0 V} \\ CD_{LYADJ} \mbox{ internal = 10 } \mbox{ pF} \\ (Vs = 2.0 \mbox{ V, Rth = 30.1 }  \Omega ) \end{array}$                   | t <sub>on(delay)</sub>  | 1.0            | 1.4        | 1.8            | μs   |
| The min and max t <sub>on(delay)</sub> range<br>(Note 3)                                       | * R2 = 190 kΩ, R3 = 57 kΩ<br>* R2 = 499 kΩ, R3 = 39 kΩ<br>(*See Figure 27)  | t <sub>on(range)</sub>  | 0.45<br>-      |            | -<br>2.0       | μs   |
| The maximum and minimum input voltage operating range. (Note 3)                                | The maximum capacitance from pin 5 to ground is 25 pF.  | Vin <sub>DLYADJ</sub>   | 1.5            | -          | 4.5            | V    |
| The maximum and minimum input<br>operating current into the D <sub>LYADJ</sub> pin<br>(Note 3) |   | lin <sub>DLYADJ</sub>   | 9              | -          | 200            | μΑ   |
| The t <sub>off</sub> time delay  | $\begin{array}{l} SYNC/CS = 0 \mbox{ to } -0.5 \mbox{ V } 100 \mbox{ kHz}, 5  \mu s \\ \mbox{ pulse, Trig } = 0 \mbox{ V} \\ CD_{LYADJ} \mbox{ internal } = 10 \mbox{ pF} \\ (Vs = 2.0 \mbox{ V}, \mbox{ Rth } = 30.1 \mbox{ k}) \end{array}$ | t <sub>off(delay)</sub> | 3.1            | 4.1        | 5.1            | μs   |
| The min and max t <sub>off(delay)</sub> range<br>(Note 3)                                      | R2 = 66 k, R3 = 23.6 k<br>* R2 = 408 k, R3 = 32.4 k<br>(*See the schematic below)   | t <sub>off(range)</sub> | 0.8            | -          | -<br>4.6       | μs   |

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#### PACKAGE DIMENSIONS



- NOTES:
  DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
  CONTROLLING DIMENSION: MILLIMETER.
  DIMENSION A AND B DO NOT INCLUDE MOLD PROTRUSION.
  MAXIMUM MOLD PROTRUSION 0.15 (0.006) PER SIDE.
  DIMENSION D DOES NOT INCLUDE DAMBAR PROTRUSION. ALLOWABLE DAMBAR PROTRUSION SHALL BE 0.127 (0.005) TOTAL IN EXCESS OF THE D DIMENSION AT MAXIMUM MATERIAL CONDITION.
  751-01 THRU 751-06 ARE OBSOLETE. NEW STANDARD IS 751-07.

|     | MILLIMETERS |      | INCHES    |       |  |  |  |
|-----|-------------|------|-----------|-------|--|--|--|
| DIM | MIN         | MAX  | MIN       | MAX   |  |  |  |
| Α   | 4.80        | 5.00 | 0.189     | 0.197 |  |  |  |
| В   | 3.80        | 4.00 | 0.150     | 0.157 |  |  |  |
| С   | 1.35        | 1.75 | 0.053     | 0.069 |  |  |  |
| D   | 0.33        | 0.51 | 0.013     | 0.020 |  |  |  |
| G   | 1.27 BSC    |      | 0.050 BSC |       |  |  |  |
| н   | 0.10        | 0.25 | 0.004     | 0.010 |  |  |  |
| J   | 0.19        | 0.25 | 0.007     | 0.010 |  |  |  |
| ĸ   | 0.40        | 1.27 | 0.016     | 0.050 |  |  |  |
| м   | 0 °         | 8 °  | 0 °       | 8 °   |  |  |  |
| N   | 0.25        | 0.50 | 0.010     | 0.020 |  |  |  |
| S   | 5.80        | 6.20 | 0.228     | 0.244 |  |  |  |

#### **SOLDERING FOOTPRINT\***



\*For additional information on our Pb-Free strategy and soldering details, please download the ON Semiconductor Soldering and Mounting Techniques Reference Manual, SOLDERRM/D.